### Plasma Current Ramp-up by the Vertical Field and Heating Power in the CTF Device

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IPR98

#### **1. Recent progress of CS-less operation in Japan**

# [1] In TST-2 spherical tokamak, the plasma current up to 10 kA has been achieved by the vertical field and ECRH.



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"Plasma Current Start-up by ECW and Vertical Field in the TST-2 Spherical Tokamak"

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[2] Recently, in the CS-less operation without any inner VT coil, the plasma current up to 110 kA has been achieved by ECRH and vertical field in JT60-U. (Takase, Mitarai, Ide, Suzuki et al) Model calculation predicted 140 kA.

#### 2. Formula for calculation

#### [1] Plasma circuit equation with vertical field and divertor coils (for initial start-up phase)

$$L_{p} \frac{dI_{p}}{dt} \quad R_{p}(I_{p} \quad I_{CD} \quad I_{BS}) \qquad M_{PV} \frac{dI_{V}}{dt} \quad M_{Psh} \frac{dI_{sh}}{dt} \quad M_{Pdiv} \frac{dI_{div}}{dt}$$

$$I_{CD} \quad \frac{CD}{nR_{o}} P_{CD}, \quad CD = 1.25 \times 10^{19} \text{ [Am}^{-2} \text{W}^{-1}\text{]}, \quad f_{BS} \quad I_{BS} / I_{p} \quad C_{BS} \sqrt{p}$$

$$C_{BS} = 0.6, \quad R_{p} \qquad NC \quad \frac{2}{a^{2}}$$

- [2]. Equivalent plasma circuit method (for overall knowledge)  $_{div} = I_{div}/I_p$  and  $_{sh} = I_{sh}/I_v$ ,  $B_{VE}$   $B_{zoV}I_V$   $B_{zosh}I_{sh}$   $B_{zodiv}I_{div}$   $L_{peff} \frac{dI_p}{dt} = R_{peff}I_p = \frac{M_{PV}}{B_{zoV}} \frac{M_{Psh-sh}}{B_{zosh-sh}} \frac{dB_{VE}}{dt} = L_{peff} - L_p - M_{Pdiv} = \frac{M_{PV}}{B_{zoV}} \frac{M_{Psh-sh}}{B_{zosh-sh}} - B_{zodiv} - div$  $L_p = 0.580 \times 10^{-6}$  H,  $L_{peff} = 0.595 \times 10^{-6}$  H.
- [3]. Separate coil current method (for second, divertor coil activation phase)

$$L_{p}\frac{dI_{p}}{dt} = R_{peff}I_{p} = \frac{M_{PV}}{B_{zoV}}\frac{M_{Psh-sh}}{B_{zoN}}\frac{dB_{VE}}{dt} = M_{Pdiv} = \frac{M_{PV}}{B_{zoV}}\frac{M_{Psh-sh}}{B_{zoV}}B_{zosh-sh}$$

#### Poloidal coil layout in CTF and simple magnetic surface for $I_{p}=10$ MA.

The total current of the divertor coil is +72 MA, and the total current of the shaping and vertical field coil are -8 MA, respectively



#### 2.3. **0-D particle and energy balance equations with control algorithm**

$$\begin{aligned} \frac{\mathrm{dn}_{\mathrm{T}}(0)}{\mathrm{dt}} &= (1 + \ _{\mathrm{n}}) \, \mathrm{S}_{\mathrm{T}}(t) - (1 + \ _{\mathrm{n}}) \, \mathrm{n}_{\mathrm{D}}(0) \mathrm{n}_{\mathrm{T}}(0) \overline{< \mathrm{v}_{\mathrm{D}\mathrm{T}}(x)} - \frac{\mathrm{n}_{\mathrm{T}}(0)}{\mathrm{T}^{*}} \\ \frac{\mathrm{dn}_{\mathrm{D}}(0)}{\mathrm{dt}} &= (1 + \ _{\mathrm{n}}) \, \mathrm{S}_{\mathrm{D}}(t) - (1 + \ _{\mathrm{n}}) \, \mathrm{n}_{\mathrm{D}}(0) \mathrm{n}_{\mathrm{T}}(0) \overline{< \mathrm{v}_{\mathrm{D}\mathrm{T}}(x)} - \frac{\mathrm{n}_{\mathrm{D}}(0)}{\mathrm{D}^{*}} \\ \frac{\mathrm{dn}_{\mathrm{t}}(0)}{\mathrm{dt}} &= (1 + \ _{\mathrm{n}}) \, \mathrm{n}_{\mathrm{D}}(0) \, \mathrm{n}_{\mathrm{T}}(0) \overline{< \mathrm{v}_{\mathrm{D}\mathrm{T}}(x)} - \frac{\mathrm{n}_{\mathrm{t}}(0)}{\mathrm{s}} \\ \frac{\mathrm{dT}_{\mathrm{t}}(0)}{\mathrm{dt}} &= (1 + \ _{\mathrm{n}}) \, \mathrm{n}_{\mathrm{D}}(0) \, \mathrm{n}_{\mathrm{T}}(0) \overline{< \mathrm{v}_{\mathrm{D}\mathrm{T}}(x)} - \frac{\mathrm{n}_{\mathrm{t}}(0)}{\mathrm{s}} \\ \frac{\mathrm{dT}_{\mathrm{t}}(0)}{\mathrm{dt}} &= \frac{1 + \ _{\mathrm{n}} + \ _{\mathrm{T}}}{1.5 \, \mathrm{e} \, (\mathrm{f}_{\mathrm{D}} + \ _{\mathrm{T}} + 1 / \ _{\mathrm{t}} + \ _{\mathrm{T}}) \, \mathrm{n}_{\mathrm{e}}(0)} \left[ \mathrm{P}_{\mathrm{EXT}} / \mathrm{V}_{\mathrm{o}} + \overline{\mathrm{P}} + \overline{\mathrm{P}}_{\mathrm{oh}} - \left\{ \overline{\mathrm{P}}_{\mathrm{L}} + \overline{\mathrm{P}}_{\mathrm{b}} + \overline{\mathrm{P}}_{\mathrm{S}} \right\} \right] \\ &- \frac{\mathrm{T}_{\mathrm{t}}(0)}{(\mathrm{f}_{\mathrm{D}} + \mathrm{f}_{\mathrm{T}} + 1 / \ _{\mathrm{t}} + \ _{\mathrm{T}}) \, \mathrm{n}_{\mathrm{e}}(0)} \left[ \left\{ 1 + \frac{1}{\mathrm{t} \, (1 - (1 + \ _{\mathrm{n}}) \mathrm{Z}\mathrm{f}_{\mathrm{imp}})} \right\} \frac{\mathrm{dn}_{\mathrm{D}}(0)}{\mathrm{dt}} + \left\{ 1 + \frac{1}{\mathrm{t} \, (1 - (1 + \ _{\mathrm{n}}) \mathrm{Z}\mathrm{f}_{\mathrm{imp}})} \right\} \frac{\mathrm{dn}_{\mathrm{t}}(0)}{\mathrm{dt}} \right\} \right] \\ \end{array} \right] \\$$

#### Confinement time

$$\begin{cases} \sum_{\substack{\text{IPB}(y,2)}} [s] = \sum_{\substack{\text{HH}}} 0.0562 \text{ A}_{i}^{0.19} \text{ I}_{p}^{0.93} [\text{MA}] \tilde{n}_{19}^{0.41} [x 10^{19} \text{m}^{-3}] \text{ R}^{1.97} [\text{m}]^{-0.58} [\text{m}] x^{-0.78} \text{ B}_{t}^{0.15} [\text{T}] / P_{\text{HT}}^{-0.69} [\text{MW}] \\ \sum_{\substack{\text{NA}}} [s] = 7.1 \ 10^{-22} \, \tilde{n} [\text{ cm}^{-3}] \text{ R}^{2.04} [\text{cm}] a^{1.04} [\text{cm}] \sqrt{q(a)} \end{cases}$$

$$\begin{bmatrix} 1 \\ \text{E} = \min\{ \sum_{\substack{\text{NA}}, \sum_{\substack{\text{IPB}(y,2)}} [\text{First part}] \\ \text{(Second part)} \\ [3] \ 1 / \sum_{\substack{\text{E}}}^{2} = 1 / \sum_{\substack{\text{NA}}}^{2} + 1 / \sum_{\substack{\text{IPB}(y,2)}} [\text{NOt in use here}] \end{cases}$$

(1) External heating power (Mainly preprogram in this study)

 $P_{\text{EXT}}(\text{HL}) [W] = M_{\text{HL0}}(t) \times 10^6 \,\overline{P}_{\text{thresh}} - (\overline{P}_{\text{oh}} + \overline{P} - \overline{P}_{\text{b}} - \overline{P}_{\text{s}}) \,V_{\text{o}}$ 

with H-mode power threshold  $M_{HL0}=15$ 

 $\overline{P}_{thresh}$  [MW] = 2.84  $\overline{n}^{0.58}$  [10<sup>20</sup> m<sup>-3</sup>] B<sub>t</sub><sup>0.82</sup> [T] R<sup>1.0</sup>[m] a<sup>0.81</sup>/A<sub>i</sub>

(2) Current drive power (PI control  $T_{int}$ =5 sec)  $P_{CD}(I_p) = 100 \times 10^6 G_{PCD} \left\{ e_{IP,n} + \frac{1}{T_{IPint}} \bigoplus_{i=0}^{n-1} e_{IP}(i \ T) \ T \right\}$   $e_{IP}(t) = \left( 1 - \frac{I_p(t)}{I_p(t)} \right)$ 

The actual heating/current drive power  $P_{cD}$  is determined by the maximum value  $P_{cD} = \max \{P_{EXT}(HL), P_{CD}(I_p)\}$ 

(3) Fueling control (PID control  $T_{int}$ =3 sec,  $T_d$ =0.01~1 sec)  $S_{DT}(t) = S_{DT0}G_{SDT}(t) \left\{ e_{Pf}(n \ T) + \frac{1}{T_{DTint}} \bigoplus_{i=0}^{n-1} e_{Pf}(i \ T) \ T + \frac{T_{DTd}}{T} \left( e_{Pf}(n \ T) - e_{Pf}((n-1) \ T) \right) \right\}$  $e_{Pf}(t) = \left( 1 - \frac{P_f(t)}{P_{fo}(t)} \right)$ 

#### Table 1. CTF assumed plasma parameters

Major radius:	R= 1.2 m	Enhancement factor:	
Minor radius:	a = 0.8 m	Peak electron density:	
Aspect ratio:	A = 1.5	Greenwald density limit1:	
Toroidal field:	$B_t = 2.5 T$	Peak temperature:	
Elongation:	= 3	Effective ion charge:	
Internal inductance	<sub>i</sub> = 0.5	<b>Confinement time</b>	
Plasma current:	$I_p \sim 10 \ MA$	Fusion power	Р
Temperature ratio:	$_{i} = T_{i} / T_{e} = 0.95$		
Density profile:	<sub>n</sub> = 0.5		
Temperature profile:	<sub>T</sub> = 1.0		

 $\label{eq:HH} \begin{array}{l} _{HH} = 0.6 \sim \!\! 2.2 \; (IPB98(y,2)) \\ n(0) \sim 3.6 \; x 10^{20} \; m^{-3} \\ n_{GW} \sim 6.8 x 10^{20} \; m^{-3} \; (for \; I_p = 10 \; MA) \\ T_i(0) \sim 15 \; keV \\ Z_{eff} \sim 1.3 \\ _E \sim 0.6 \sim \! 0.7 \; s \\ P_f = 300 \; MW \end{array}$ 

Plasma inductance ( = 3)	$L_p \sim 0.589$ H		
Mutual inductance between PF	3 coil and plasma:	$M_{PV}$ = 6.08x10 <sup>-6</sup> H/A,	$B_{zoV}$ =1.33x10 <sup>-6</sup> T/A
Mutual inductance between Pl	F2 coil and plasma:	$M_{Psh} = 2.91 \times 10^{-6} \text{ H/A},$	$B_{zosh} = 0.631 \times 10^{-6} \text{ T/A}$
Mutual inductance between PF	1 coil and plasma:	M <sub>Pdiv</sub> =0.132x10 <sup>-6</sup> H/A,	$B_{zodiv} = 0.0272 \times 10^{-6} \text{ T/A}$

#### **3. Calculated results**

#### 3.1. Equivalent circuit model ( <sub>E</sub>=min{ <sub>NA</sub>, <sub>IPB98</sub>})

For  $_{CD} = 0 \ [Am^{-2}W^{-1}]$ , the external heating power of 37 MW together with the fusion power up to 300 MW increases the plasma current up to 10 MA. As the non-inductive driven current does not exist in this case and the bootstrap current is ~80 % (for  $C_{_{BS}}=0.6$ ), the plasma current is slowly reduced after peak of 10 MA.



## When the heating power is slightly decreased to 35 MW, the operating point can be reached but the oscillation in plasma parameters takes place.



When the heating power is further decreased to 33 MW, the steady operating point cannot be obtained because the plasma parameter oscillation grows and the discharge is eventually terminated.



The reason of these oscillations and termination is understood using POPCON. As the height of the contour line during accessing the operating point is high for NA, it is difficult to reach the operating point with the smaller heating power.



When the non-inductive current drive efficiency with  $_{CD} = 1.25 \times 10^{19} [Am^{-2}W^{-1}]$  exists, the same plasma current should be obtained by the smaller heating power than 37 MW. However, the discharge is terminated with  $P_{EXT}$ =37 MW and needs 40 MW. This is in contradiction to our intuition.



**Reason:** During discharge, the Neo-Alcator scaling is dominant. Therefore, the larger plasma current decreases the confinement time through the Neo-Alcator scaling with q<sup>0.5</sup> (q is the safety factor), leading to necessity of larger heating /current drive power.

#### 3.2. Separate coil current method with $_{E}=\min\{ _{NA}, _{IPB98}\},$

The null point is created when the coil current ratio is maintained. In the outward region of this null point, the normal vertical field for equilibrium is generated. (No vacuum chamber current effect). The null point moves inward with time.



The magnetic field vector in the breakdown phase;

(a)  $I_{PF1}$ =+80 kA total,  $I_{PF2}$ =-6.4 kA total, and  $I_{PF3}$ =0 kA, (b)  $I_{PF1}$ =+80 kA total,  $I_{PF2}$ =-6.626 kA total, and  $I_{PF3}$ =-0.215 kA total, (c)  $I_{PF1}$ =+80 kA total.  $I_{PF2}$ =-6.85 kA total, and  $I_{PF3}$ =-0.429 kA total

#### [1] Initial phase controlled by PF1, PF2 and PF3 coils.

The plasma current is ramped up to ~0.67 MA when  $I_{PF1}(total) =+80 \text{ kA}$  is maintained,  $I_{PF2}(total) = -6.4 \text{ kA} \rightarrow -320 \text{ kA}$  $I_{PF3}(total) = 0 \quad \text{kA} \rightarrow -320 \text{ kA}$ 



@ Initial phase is determined by IPB(y,2) scaling.

#### [2] Divertor coil activation phase $_{E}=\min\{_{NA},_{IPB98}\},$

When the divertor coil current  $I_{div}$  reaches  $_{div}I_p$ , it is now set to be proportional to the plasma current with  $_{div}$  = 1.8. Reverse induction by divertor coil is not large.



#### [3] The long time behavior up to 100 s ( $P_{EXT}$ = 45 MW, <sub>cD</sub> = 0 [Am<sup>-2</sup>W<sup>-1</sup>], <sub>E</sub>=min{ <sub>NA</sub>, <sub>IPB98</sub>},)

The plasma current of 10 MA is finally obtained. (We should note that the slower ramp rate of the fusion power can reduce the heating power to the operating point with  $P_{EXT}$  =43 MW and  $t_{ramp}$ =200 sec.)



# 3.3. Separate coil current method with E IPB98 [1] CD = 0 [Am<sup>-2</sup>W<sup>-1</sup>], P<sub>EXT</sub>=45 MW, HH = 1.9, (T<sub>d</sub>=0.5 s, T<sub>int</sub>=3 s) When no current drive exists, 45 MW is needed to obtain 10 MA. (Note: Density and temperature has no steady state.)



#### [2] $_{CD} = 1.25 \times 10^{19} [Am^{-2}W^{-1}], P_{EXT} = 30 MW, HH = 1.9, (T_{d} = 0.1 s, T_{int} = 3 s)$

On the other hand, if the current drive capability exists, the heating/current drive power can be reduced to 30 MW for 10 MA ramp-up. IPB(y,2) scaling provides reasonable results with respect to the plasma current.



# [3] Second phase is unstable for IPB(y,2) scaling. Careful adjustment of the PID parameter in fueling control is necessary.

 $_{CD} = 0 [Am^{-2}W^{-1}], P_{EXT} = 45 MW, HH = 1.9, (T_{d} = 0 s, T_{int} = 3 s)$ 



## [4] Steady state of 10.5 MA after 100 sec is maintained by the feedback control of the non-inductive drive power.

 $_{CD} = 1.25 \times 10^{19} [Am^{-2}W^{-1}], HH = 1.9, P_{EXT} = 30 MW to 70 MW, (T_{d} = 0.1 s, T_{int} = 3 s)$ 



#### 4. Summary and further issues

[1] The plasma current ramp up to 10 MA is possible with the heating power of 30~45 MW in the CTF device without the central solenoid for these scalings.

[2] It is confirmed that the equivalent circuit equation model and separate poloidal coil circuit model provide the similar results with 0-D equation.

[3] The plasma current of ~600 kA could be obtained in the initial phase by outer poloidal coil activation.

[4] Discharge behaviors based on the minimum selection of the confinement time of NA and IPB provides the contradictory results.

IPB scaling provides the reasonable behaviors except for the second phase. (Careful choice of the derivative time for fueling is necessary in the second phase.)

[5] For steady state operation, more heating/current drive power is required. Further optimization would be necessary to reduce the power.